Overview		System design and requirements		
•				

Development of a Helium Gas Balloon Flying System for Aerial Photographing and Observation

Elie N. Mambou, G. Yamga, J. Meyer & H. C. Ferreira

Department of Electrical and Electronic Engineering Science, University of Johannesburg

8th International Conference on Communication Software and Networks

Beijing, China.

June 4-6, 2016.





Overview 0	About me!	System design and requirements	System implementation	Results 000000	Summary 000	
Abou	t me!					

- Belong to Center for Telecommunications (Dept. Electrical and Electronic Eng., Univ. of Johannesburg, South Africa).
- Research interests include but not limited to: Coding theory, Shannon theory, Networking, Encoding/Decoding coding, wireless communication, computer systems...



Overview	About me!	System design and requirements		

Overview



Introduction

- Aerial observation of the atmosphere
- Aim of project
- 2 System design and requirements
 - Helium gas balloon
 - Sensing and tracking subsystem
 - System implementation
 - Tracking and sensing subsystems
 - Implemented system read for launch
- 4 Results
 - Launching position
 - Aerial photos
 - Photos at the highest altitude
 - Observations
 - Analysis
- 5 Summary

Overview Abou	it me! Introduction	System design and requirements	System implementation	
	0			

Aerial observation unmanned systems

This refers to systems made for photographing of the atmosphere from high or low altitude; and send real time data to base station. They have many advantages like:

- Vegetation survey and weather predictions;
- Can be used for surveying disaster areas in case of earthquake, volcano, tsunami, typhoon;

There are many types of unmanned systems based on the application:

- Flying balloon systems: can fly continuously, reach steady buoyancy, suitable for high altitude, system control is very unstable.
- Unmanned aerial vehicles (UAVs or drones): autonomous control, can not fly for long time, stabilization endurance, suitable for low altitude.
- balloon drone systems: combination of balloon systems and drones features.

Overview 0		Introduction $\circ \bullet$	System design and requirements	System implementation	Results 000000	Summary 000
Aim	of proje	ect				

Design a low cost flying system to achieve aerial photographing at the highest possible altitude above sea level.

The helium gas balloon was chosen for this task over other gases because of the following:

- Helium is less heavy than air; so the helium balloon due to less weight should ascend quicker in atmosphere according to Archimedes principles.
- Helium is an inert gas, environmentally friendly and less explosive than hydrogen or methane.

Overview O		System design and requirements ●○	System implementation	Results 000000	

Helium gas balloon

The overall mechanism is made of a helium gas balloon connected by a rope to the payload containing 2 subsystems: the tracking and sensing subsystems.

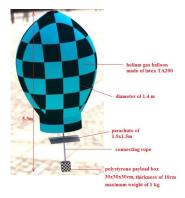


Figure: Balloon design

Overview		System design and requirements	System implementation	
		Õ•		

Sensing and tracking subsystem

The sensing subsystem was designed to read the temperature and the atmospheric pressure at regular time intervals of 10 seconds. Tracking subsystem for monitoring GPS location and taking photos during flight.



Figure: Sensing and tracking system

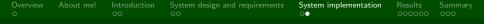
Overview		System design and requirements	System implementation	Results	
			0		

Tracking and sensing subsystems

altitude = $44330 * \left(1 - \left(\frac{p}{p_0}\right)^{\frac{1}{5.255}}\right)$, computes the altitude from the sensed atmospheric pressure p; and $p_0 = 101325$ Pa at sea level.

File Edit Format View Help	HTMLVIEwer
Number: 1 Altitude: 1378.36 m Other Readings Femperature: 27.98 deg C Pressure: 85843 Pa	Result(i=7, result=(upps: (ubearing: 184,0990594824242); usinute: 1340810580548, usinute: 1340810580548, using/tuber is using/tuber usi
Number: 2 Altitude: 1376.93 m	
Temperature: 28.10 deg C Pressure: 85870 Pa	
Number: 3 Altitude: 1374.35 m	
Temperature: 28.30 deg C Pressure: 85866 Pa	

Figure: Textfiles from sensing and tracking subsystems



Implemented system read for launch

During the first test on the 29/10/2012...

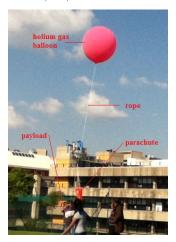


Figure: Implemented system

Overview 0		System design and requirements	System implementation 00	Results ●00000	

Launching position

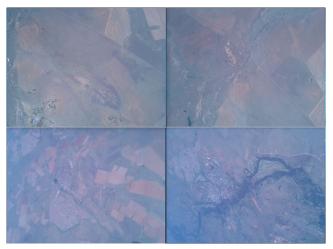
The system was launched on a safe grass field in Parys, Free State, South Africa (wind direction SE, cloud cover 0/7, atmospheric pressure 104.7 kPa, average temperature 24° C).

- launching point: atitude:-26.97, longitude:27.31 and altitude:1443 metres above sea level
- launching date: 3rd November 2012.



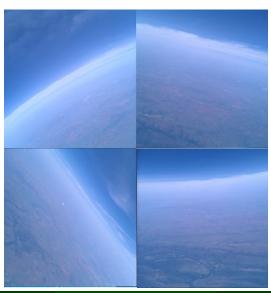
Aerial random photos from payload

Photos from payload during the ascent,





Photos at the highest altitude, 13.7821 km above sea level



Overview 0		System design and requirements	System implementation	Results ○○○●○○	
	-				

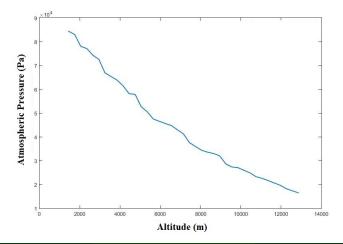
Observations

- The highest altitude was recorded at an altitude of 13.7821 km (45216.86 feet) above sea level at a point of latitude -26.69 and longitude 27.47.
- The payload landed back at beginning of December 2012 in the outskirts of Vereeniging (Gauteng Province, South Africa) around the point (latitude: -26.40, longitude: 27.55 and altitude: 1479 metres above sea level), this is approximately 125 km away from the launching position.
- The tracking subsystem was surrounded by insulation materials to avoid temperature dissipation at high altitude.
- The payload was ascending up with an average velocity of 5.5 m/s.
- The batteries or power supplies of the tracking and sensing subsystems were fully charged before the flight.



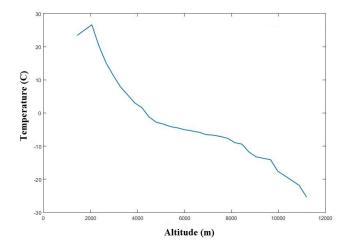
Pressure vs. altitude during flight

Sensor reading is not perfectly accurate, as result of no QNH correction, offset range is 2%.





Temperature vs. altitude during flight



Overview 0		System design and requirements	System implementation	Results 000000	

Summary

- The highest altitude reached by our payload was 13.78 km.
- The world record of helium gas balloon flying system is about 30 km.
- Although our mechanism achieved less than records, it is ideal and advisable design approach for university projects or research laboratories in order to expose young engineering students to more practice as our design was based on low cost components.

Overview 0		System design and requirements	System implementation	Results 000000	
Refer	ences I				

- S. Kubo, A. Sakaguch, and T. Takimoto, "Development of flying observation system with helium gas balloon and tilt rotors", in *Proc. Int. Conf. on Control, Automation and Systems*, Gyeonggi-do, Korea, Oct. 22–25, 2014, pp. 1627–1630.
- T. G. Guzik, "The High Altitude Student Platform (HASP) as a Model Multi-Payload Balloon Platform", in *IEEE Aerospace Conference*, Big Sky, Montana, Mar. 7–14, 2015, pp. 1–10.
 - B. Silva et al., "Mapping Two Competing Grassland Species from a Low-Altitude Helium Balloon", *IEEE Journal of Selected Topics in Applied Earth Observations and Remote Sensing*, vol. 7, no. 7, pp. 3038–3049, May 2014.



"We cannot solve our problems with the same thinking we used when we created them." Albert Einstein

QUESTIONS AND COMMENTS

